

McGINN & GIBB, PLLC
A PROFESSIONAL LIMITED LIABILITY COMPANY
PATENTS, TRADEMARKS, COPYRIGHTS, AND INTELLECTUAL PROPERTY LAW
8321 OLD COURTHOUSE ROAD, SUITE 200
VIENNA, VIRGINIA 22182-3817
TELEPHONE (703) 761-4100
FACSIMILE (703) 761-2375; (703) 761-2376

**APPLICATION
FOR
UNITED STATES
LETTERS PATENT**

APPLICANT'S: **TATSUNORI NAGURA**
 HARUO FUJIKI

FOR: **DRIVING FORCE DISTRIBUTION
CONTROL DEVICE FOR VEHICLE**

DOCKET NO.: **US-P1732F**

DRIVING FORCE DISTRIBUTION CONTROL DEVICE FOR VEHICLE

The disclosure of Japanese Patent Application No. 2002-275531 filed on September 20, 2002 including the specification, drawings and abstract is incorporated herein by reference in its entirety.

BACKGROUND OF THE INVENTION

1. Field of the Invention

10 The present invention relates to a driving force distribution control device for a vehicle which controls engaging force of a coupling mechanism so as to change transmission torque, and distributes driving force.

2. Description of the Related Art

15 Conventionally, with a driving force transmission system for four-wheel-drive vehicles and so forth, a system has been known wherein a coupling mechanism made up of a multiple disc clutch and the like is disposed within a transfer, and controlling engaging torque of this coupling
20 mechanism continuously controls distribution of driving force toward the rear wheel side.

With such a system, a torque limiter for limiting engaging torque of the coupling mechanism is provided. For example, Japanese Patent No. 2,599,965 discloses art wherein,
25 with a four-wheel-drive vehicle having a center differential

for dividing driving force output from the engine so as to transmit the divided force to a front-wheel-drive system and a rear-wheel-drive system, a mechanical torque limiter is disposed on the rear-wheel-drive system (or the front-wheel-drive system), and while this torque limiter is running, limiting differential of the center differential enables jack-rabbit starts and rapid acceleration.

However, the conventional torque limiter fixes the transmission torque at a constant value, so in the event of mounting nonstandard-diameter tires or in the event of performing specific control in a state wherein oil temperature of the differential (especially the rear differential) rises abnormally, deterioration of driving performance is brought about, and also in the event of transition from an ordinary control state to a specific control state or in the event of switching of the control state at recovery from the specific control state to the ordinary control state, the engaging torque is drastically changed, thereby causing problems such as deterioration for driving stability and driving performance.

SUMMARY OF THE INVENTION

Accordingly, it is an object of the present invention to provide a driving force distribution control device for a vehicle wherein adverse effects on driving stability and

driving performance, under a specific control state for protecting a driving force transmission system, can be kept to a minimum.

Briefly, the driving force distribution control device
5 for a vehicle according to the present invention, comprises:
means for continuously changing a torque limiter which
limits engaging force of the coupling mechanism, from a
limiter value in an ordinary control state according to a
driving state, to a limiter value in a specific control
10 state for protecting a driving force transmission system;
and means for controlling engaging force of the coupling
mechanism in the specific control state so as to keep below
the limiter value in the specific control state.

Other features and advantage of the present invention
15 will become sufficiently clear by the following description
in detail.

BRIEF DESCRIPTION OF THE DRAWINGS

Fig. 1 is a schematic configuration diagram of a
20 system;

Fig. 2 is a flowchart of torque limiter control
processing; and

Fig. 3 is an explanatory diagram which illustrates a
control region by a torque limiter.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

First of all, description will be made with regard to a driving force transmission system for a four-wheel-drive vehicle, with reference to Fig. 1. In the drawing,

5 reference numeral 1 denotes an engine, and a transmission 2 is connected to the output axis of the engine 1. A transfer 3 is integrally linearly connected to the rear portion of the transmission 2. The transfer 3 comprises a center differential with a planetary gear mechanism 4 to which

10 driving force is input from a transmission 2, and a transfer clutch 5 made up of a multiple disc clutch with engaging torque computerized by a transfer control unit 20 described later as a coupling mechanism, linearly connected to the planetary gear mechanism 4. Following the output from the

15 engine 1 being shifted to the predetermined gear by the transmission 2, the driving force is distributed to the front wheel side and the rear wheel side via the transfer 3.

With this configuration, the output side of the transmission 2 is connected to a ring gear of the planetary gear mechanism 4, and a carrier which supports rotatable pinions meshing with this ring gear and a sun gear is connected to a rear differential 7 via a propeller shaft 6. Moreover, a carrier of the planetary gear mechanism 4 is connected to a clutch drum of the transfer clutch 5, and the

25 sun gear is connected to a clutch hub of the transfer clutch

5, and also connected to a front differential 9 via a front drive shaft 8.

The transfer clutch 5 comprises a driving mechanism for pressing a detachable clutch plate disposed in a row between 5 the clutch drum and the clutch hub via the carrier, which comprises an electromagnetic driving mechanism made up of an electromagnetic clutch and a cam for amplifying torque, so that controlling the exciting current of this electromagnetic driving mechanism controls the engaging 10 torque.

Moreover, the driving force input from the transmission 2 to the planetary gear mechanism 4 is transmitted to the left and right rear wheels 11L and 11R via the carrier through the rear differential 7, and also differential 15 output between the carrier corresponding to the engaging force of the transfer clutch 5 and the sun gear is transmitted to the left and right front wheels 10L and 10R via the front differential 9. That is to say, in the event that the transfer clutch 5 is in a complete engaging state, 20 the carrier and the sun gear are integrally fixed so as to perform even distribution of torque to the front wheel side and the rear wheel side, and in the event that the transfer clutch 5 is in a disengaged state, torque is disproportionately distributed to the rear wheels.

25 The engaging torque from the transfer clutch 5

computerized by the transfer control unit 20 primarily made up of a microcomputer. Signals from various kinds of sensors and switches and so forth for detecting an engine running state and a driving state, and control signals from 5 other control units and the like are input to this transfer control unit 20, with an instruction value for engaging torque being calculated based on these signals.

The signals input to the transfer control unit 20, as shown in Fig. 1, include signals from a wheel speed sensor 10FR for detecting wheel speed of the right front wheel 10R, a wheel speed sensor 10FL for detecting wheel speed of the left front wheel 10L, a wheel speed sensor 10RR for detecting wheel speed of the right rear wheel 10R, a wheel speed sensor 10RL for detecting wheel speed of the left rear wheel 10L, a throttle opening sensor 22 for detecting opening of a throttle valve of the engine 1, a brake switch 23 which is turned on by stepping on a brake pedal, a hand brake switch 24 which is turned on by pulling a hand brake lever, an ABS actuating signal from an ABS control unit 30, 20 a lateral acceleration sensor 25 for detecting acceleration in a lateral direction of the vehicle, an oil temperature switch 26 which turns on in the event that the oil temperature exceeds a preset temperature and enters a high temperature state, and so forth.

25 With the above-described engaging torque control of the

transfer clutch 5, special processing for protecting a driving force transmission system such as the transmission 2, transfer 3, rear differential 7, and front differential 9 is not required, and a variable torque limiter, which
5 continuously changes in both an ordinary control state wherein the engaging torque of the transfer clutch 5 is controlled according to a driving state, and a specific control state wherein the engaging torque of the transfer clutch 5 must be reduced so as to protect the driving force
10 transmission system, is provided.

Moreover, in the event of transition from the ordinary control state to the specific control state or in the event of recovery from the specific control state to the ordinary control state, controlling the engaging torque of the
15 transfer clutch 5 so as to be restrained below the variable torque limiter in all states avoids excessive change of engaging torque, and avoids excessive rise in oil temperature in each portion and deterioration of performance of each part, thereby suppressing deterioration of driving
20 stability and driving performance.

Now, the control states indicated by the following (1) through (3) are representative examples of specific control.

(1) A control state when mounting nonstandard-diameter tires wherein the left and right front wheels 10L and 10R,
25 and left and right rear wheels 11L and 11R, are not the same

in tire size.

(2) A control state wherein abnormal rise in oil temperature is detected by any of the transmission 2, transfer clutch 5, rear differential 7, or front 5 differential 9.

(3) A control state when abnormal differential rotation between the front and rear wheels is detected in a state of the transfer clutch 5 being engaged to a certain degree (for example, a control state such as jack-rabbit 10 starts with moderate opening of the accelerator, or a control state when driving on an uneven road surface such as a dirt road or the like).

The following description will be made with regard to torque limiter control processing by the transfer control 15 unit 20, with reference to the flowchart shown in Fig. 2.

In this torque limiter control processing, first of all, in Step S101, confirmation is made with regard to whether or not a specific control state such as at mounting nonstandard-diameter tires or the like is currently 20 determined. For example, in the event that mounting of nonstandard-diameter tires is determined based on signals from the front and rear wheel speed sensors 21FR, 21FL, 21RR, and 21RL, confirmation is made whether or not transition from the ordinary control state to the specific control 25 state has been performed by this mounting nonstandard-

diameter tires, or whether or not transition from the specific control state to the ordinary control state by disengaging the determination.

Moreover, in the event of the determination for the 5 specific control state is made, the processing proceeds from Step S101 to Step S102, where confirmation is made whether or not the present torque limiter value exceeds the maximal torque value allowed at the specific control state. The maximal torque value allowed at the specific control state 10 is the maximal torque value capable of protecting the driving force transmission system, so taking the output from the engine or the configuration of the driving force transmission system or the like into consideration, this value is set beforehand as the maximal torque value wherein 15 oil temperature at each unit, and the oil temperature of the rear differential 7 in particular, does not exceed the preset temperature for mounting nonstandard-diameter tires.

Consequently, in the event that the present torque limiter value does not exceed the maximal torque value 20 allowed at the specific control state, the processing proceeds from Step S102 to Step S107. Also, in the event that the present torque limiter value exceeds the maximal torque value allowed at the specific control state, the processing proceeds from Step S102 to Step S103, where the 25 torque limiter value is updated by subtracting the

predetermined constant A1 from the present torque limiter value, which lowers the torque limiter value slowly toward the maximal torque value allowed at the specific control state, and the processing proceeds to Step S107.

- 5 In Step S107, confirmation is made whether or not the instruction value of the engaging torque (center differential instruction torque) of the transfer clutch 5 which is set according to the driving state of the vehicle, for example, the center differential instruction torque
10 which is set based on the load on the engine such as throttle opening or the like and the vehicle speed, exceeds the torque limiter value. In the event of the center differential instruction torque does not exceed the torque limiter value, the processing escapes from the routine
15 without changing the center differential instruction torque, and in the event that the center differential instruction torque exceeds the torque limiter value, the processing proceeds from Step S107 to Step S108 so as to regulate the center differential instruction torque with the torque
20 limiter value, and then escapes from the routine.

Fig. 3 shows an example of change of the torque limiter value between the ordinary control state and the specific control state when mounting nonstandard-diameter tires.
With this example shown in Fig. 3, in the event of
25 determining the mounting state of nonstandard-diameter tires

with regard to the torque limiter value in the ordinary control state shown with the line L1, the torque limiter value is lowered slowly up to the line L2, and even in the event of transition from the ordinary control state to the 5 specific control state, controlling the engaging torque of the transfer clutch 5 within a range from the torque limiter indicated by L1 to the torque limiter indicated by L2 avoids adverse effects on the performance of the vehicle, whereby deterioration of driving stability and driving performance 10 can be kept to a minimum.

On the other hand, in Step S101, in a state wherein the specific control state has not been determined, that is to say, in the event that determination of the specific control state is disengaged so as to make the transition to the 15 ordinary control state, the processing proceeds from Step S101 to Step S104, where the torque limiter value is updated by adding the predetermined constant A2 to the present torque limiter value, thereby raising the torque limiter value slowly up to the maximal torque limiter value at the 20 ordinary control state. Note that the maximal torque limiter value is preset as the maximal value of the engaging torque of the transfer 5 wherein performance and driving stability of each unit can be ensured, taking the output from the engine or the configuration of the driving force 25 transmission system or the like into consideration.

That is to say, as shown in Fig. 3, in the event that determination of the mounting state of nonstandard-diameter tires is disengaged so as to make the transition from the specific control state to the ordinary control state, the 5 torque limiter is raised slowly from the torque limiter value indicated by L2 up to the torque limiter value of the ordinary control state indicated by L1, whereby excessive change on the performance of the vehicle can be avoided.

In this case, the relation between the constant A2 for 10 determining variation of the torque limiter rate per time increment when making the transition from the specific control state to the ordinary control state, and the constant A1 for determining variation of the torque limiter rate per time increment when making the transition from the 15 ordinary control state to the specific control state, is suitably set according to the control state, as shown in the following cases (a) through (c).

(a) $A_2 < A_1$

In the event that transition from the ordinary control 20 state to the specific control state occurs due to an increase in oil temperature of the rear differential 7 or the like, following which the specific control state is disengaged, relatively increasing the variation of the torque limiter value rate per time increment at transition 25 from the ordinary control state to the specific control

state lowers the oil temperature immediately.

(b) $A_2 > A_1$

In the event that a state wherein nonstandard-diameter tires are mounted is determined and transition from the ordinary control state to the specific control state is made, following which the determination of the mounting state of nonstandard-diameter tires is disengaged, relatively increasing the variation of the torque limiter value rate per time increment at transition from the specific control state to the ordinary control state speeds the recovery to the ordinary control state.

(c) A_2 is approximately equal to A_1

In the low vehicle speed range, setting the variation of the torque limiter value rate per time increment at transition from the ordinary control state to the specific control state and that at transition from the specific control state to the ordinary control state generally the same, keeps adverse effects on the performance of the vehicle due to switching the control state to a minimum.

Moreover, in Step S105 following Step S104, whether or not the updated torque limiter value exceeds the maximal torque limiter value in the ordinary control state is confirmed, and in the event that the torque limiter value does not exceed the maximal torque limiter value in the ordinary control state, the processing proceeds from Step

S105 to Step S107. Also, in the event that the updated torque limiter value exceeds the maximal torque limiter value in the ordinary control state, the processing proceeds from Step S105 to Step S106, where the torque limiter value 5 is fixed to the maximal torque limiter value in the ordinary control state, then the processing proceeds to Step S107.

As described above, in Step S107, whether or not the center differential instruction torque which is set according to a driving state of the vehicle exceeds the 10 torque limiter value is confirmed, and in the event of not exceeding the torque limiter value, the processing escapes from the routine without changing the center differential instruction torque. Also, in the event that the center differential instruction torque exceeds the torque limiter 15 value, the processing proceeds from Step S107 to Step S108 so as to regulate the center differential instruction torque with the torque limiter value, then the processing escapes from the routine.

As described above, the torque limiter is changed 20 continuously between the ordinary control state wherein the engaging torque of the transfer clutch 5 as a coupling mechanism is controlled according to the driving state, and the specific control state wherein the driving force transmission system must be protected by reducing the 25 engaging torque of the transfer clutch 5, and the engaging

torque of the transfer clutch 5 is controlled to keep below this torque limiter value, whereby excessive change of torque at transition between the ordinary control state and the specific control state can be avoided, and moreover, 5 adverse effects on driving stability and driving performance under the specific control state can be kept to a minimum.

Further, with the present invention, it is apparent that a wide range of different embodiments can be formed on the basis of the present invention without departing from 10 the spirit and scope of the present invention. The present invention is not restricted by any specific embodiment except as limited by the appended claims.